# 5339 - Algorithms design under a geometric lens Spring 2014, CSE, OSU Lecture 2: Random partitions 

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## Metric embedding examples

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Embedding into a star gives distortion $O(1)$.

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Best-possible distortion $\Omega(n)$

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## The Closest Pair problem

Given a metric space $(X, \rho)$, find a pair of minimum distance.

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Given a metric space $(X, \rho)$, find a pair of minimum distance. l.e. find $x \neq y \in X$, minimizing $\rho(x, y)$.

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Each region $S_{X}$ contains at most $O(1)$ points from $R$. Why?
For each $x \in L$, try all points in $S_{x}$.
Proceed similarly for the points in $R$.

## Running time

Total running time:

$$
T(n)=2 \cdot T(n / 2)+O(n)
$$

Therefore, $T(n)=O(n \log n)$.

## Decision version of closest pair

Given a metric space $(X, \rho)$, and some $r>0$, decide whether the min-distance is at most $r$.

A simpler algorithm for the decision version in the Euclidean plane

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A simpler algorithm for the decision version in the Euclidean plane

Let $X \subset \mathbb{R}^{2},|X|=n, r>0$.
Impose a grid in $\mathbb{R}^{2}$, where each cell is a square of side length $4 \cdot r$.


## A simpler algorithm (cont.)

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We shift the grid horizontally by $t_{x}$, and vertically by $t_{y}$.

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We shift the grid horizontally by $t_{x}$, and vertically by $t_{y}$.
I.e. we get a partition of $\mathbb{R}^{2}$ into cells $\left\{C_{i, j}\right\}_{i, j \in \mathbb{Z}}$, where

$$
C_{i, j}=\left[t_{x}+i 4 r, t_{x}+(i+1) 4 r\right) \times\left[t_{y}+j 4 r, t_{y}+(j+1) 4 r\right) .
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The probability that $x$ and $y$ are separated by a horizontal line of the grid, is at most $\frac{\|x-y\|_{2}}{4 r}$.
By the union bound, the probability that $x$ and $y$ are separated is at most $\frac{\|x-y\|_{2}}{2 r}$.

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Compute a random partition using a randomly shifted grid. There are at most $n$ non-empty cells (since there are $n$ points). If there exists a non-empty cell with at least 100 points, then it must contain a pair at distance at most $r$.

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Otherwise, for every non-empty cell $C$, check all pairs of points in C.

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If after $O(\log n)$ repetitions no pair is found, then output NO.

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Thus, after $O(\log n)$ iterations, we find $x, y$ with high probability.

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Thus, after $O(\log n)$ iterations, we find $x, y$ with high probability.
Running time: $O(n \log n)$.

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For any $x \in X$, we denote by $P(x)$ the cluster containing $x$.
Let $\beta>0$.
A $(\beta, r)$-Lipschitz partition of $(X, \rho)$ is a distribution $\mathcal{D}$ over $r$-partitions of $(X, \rho)$, such that for any $x, y \in X$ :

$$
\operatorname{Pr}_{P \in \mathcal{D}}[P(x) \neq P(y)] \leq \beta \cdot \frac{\rho(x, y)}{r}
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For any $r>0$, the space $\mathbb{R}^{2}$ admits a $(O(1), r)$-Lipschitz partition.
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What about general metric spaces?

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Pick $\alpha \in[1 / 2,1)$, uniformly at random.
For any $i \in\{1, \ldots, n\}$, let

$$
C_{i}=\operatorname{Ball}\left(x_{\sigma(i)}, \alpha \cdot r / 2\right) \backslash\left(\bigcup_{j=1}^{i-1} C_{j}\right)
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where

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\operatorname{Ball}(x, t)=\left\{y \in X:\|x-y\|_{2} \leq t\right\}
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Let $P=\left\{C_{1}, \ldots, C_{n}\right\}$ be the resulting random partition of $X$.

## Analysis

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Proof.
Each cluster is contained inside some Ball( $x_{i}, r / 2$ ). Therefore, it has diameter at most $r$.

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## Lemma

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Proof: Fix $x, y \in X$.
We say that $x_{i}$ settles $\{x, y\}$ if $x_{i}$ is the first point w.r.to $\sigma$ such that $\operatorname{Ball}\left(x_{i}, r / 2\right) \cap\{x, y\} \neq \emptyset$.

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## Lemma

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Proof: Fix $x, y \in X$.
We say that $x_{i}$ settles $\{x, y\}$ if $x_{i}$ is the first point w.r.to $\sigma$ such that Ball $\left(x_{i}, r / 2\right) \cap\{x, y\} \neq \emptyset$.
Assume after reordering $X$, that

$$
\rho\left(x_{1},\{x, y\}\right) \leq \rho\left(x_{2},\{x, y\}\right) \leq \ldots \leq \rho\left(x_{n},\{x, y\}\right),
$$

where $\rho(z,\{x, y\})=\min \{\rho(z, x), \rho(z, y)\}$.

Proof (cont.)

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$$

In order for $P(x) \neq P(y)$ when $x_{s}$ settles $\{x, y\}$, it must be that

$$
\alpha \cdot r / 2 \in I_{s} .
$$

## Proof (cont.)

$$
\begin{aligned}
\operatorname{Pr}[P(x) \neq P(y)] & \leq \sum_{s=1}^{n} \operatorname{Pr}\left[P(x) \neq P(y) \text { and } x_{s} \text { settles }\{x, y\}\right] \\
& \leq \sum_{s=1}^{n} \operatorname{Pr}\left[\alpha \cdot \rho / 2 \in I_{s} \text { and } x_{s} \text { settles }\{x, y\}\right] \\
& \leq \sum_{s=1}^{n} \operatorname{Pr}\left[x_{s} \text { settles }\{x, y\} \mid \alpha \cdot \rho / 2 \in I_{s}\right] \cdot \operatorname{Pr}\left[\alpha \cdot \rho / 2 \in I_{s}\right] \\
& \leq \sum_{s=1}^{n} \frac{1}{s} \cdot \frac{4 \cdot\left|\rho\left(x_{s}, x\right)-\rho\left(x_{s}, y\right)\right|}{r} \\
& \leq \sum_{s=1}^{n} \frac{1}{s} \cdot \frac{4 \rho(x, y)}{r} \\
& \leq O(\log n) \cdot \frac{\rho(x, y)}{r}
\end{aligned}
$$

We obtain the following:

## Theorem ([Bartal '96])

For any $r>0$, any $n$-point metric space admits a $(O(\log n), r)$-Lipschitz partition.

