6331 - Algorithms, Spring 2014, CSE, OSU Elementary graph algorithms

Instructor: Anastasios Sidiropoulos

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Graph problems

• Many problems can be phrased as graph problems.



Graph problems

Many problems can be phrased as graph problems.

・ロト・日本・モト・モート ヨー うへで

• Input: Graph G = (V, E).

Graph problems

- Many problems can be phrased as graph problems.
- Input: Graph G = (V, E).
- The running time is measured in terms of |V|, and |E|.

Adjacency-matrix for a graph G = (V, E).

 $|V| \times |V|$ matrix $A = (a_{ij})$, where

$$a_{ij} = \begin{cases} 1 & \text{if } \{i,j\} \in E \\ 0 & \text{if } \{i,j\} \notin E \end{cases}$$

Adjacency-matrix for a graph G = (V, E).

 $|V| \times |V|$ matrix $A = (a_{ij})$, where

$$a_{ij} = \begin{cases} 1 & \text{if } \{i,j\} \in E\\ 0 & \text{if } \{i,j\} \notin E \end{cases}$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Storage space = $\Theta(|V|^2)$.

The adjacency-list for a graph G = (V, E) is an array Adj of size |V|.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

The adjacency-list for a graph G = (V, E) is an array Adj of size |V|.

For each $u \in V$, Adj[u] is a list that contains all $v \in V$, with $\{u, v\} \in E$.

The adjacency-list for a graph G = (V, E) is an array Adj of size |V|.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

For each $u \in V$, Adj[u] is a list that contains all $v \in V$, with $\{u, v\} \in E$.

Storage space = $\Theta(|V| + |E|)$.

The adjacency-list for a graph G = (V, E) is an array Adj of size |V|.

For each $u \in V$, Adj[u] is a list that contains all $v \in V$, with $\{u, v\} \in E$.

Storage space = $\Theta(|V| + |E|)$.

Much smaller space when $|E| \ll |V|^2$.

Breadth-first search

An algorithm for "exploring" a graph, starting from the given vertex s.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

```
Breadth-first search
BFS(G, s)
   for each u \in G.V - \{s\}
      u.color = WHITE
      u.d = \infty
      u.\pi = NIL
   s.color = GRAY
   s.d=0
   s.\pi = NII
   Q = \emptyset
   ENQUEUE(Q, s) //FIFO queue
   while Q \neq \emptyset
      u = \mathsf{DEQUEUE}(Q)
      for each v \in G.Adj[u]
         if v_{.color} = WHITE
            v.color = GRAY
            v.d = u.d + 1
            v.\pi = u
            ENQUEUE(Q, v)
      u.color = BLACK
```

How many DEQUEUE operations?



 How many DEQUEUE operations? A non-white vertex never becomes white.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

How many DEQUEUE operations? A non-white vertex never becomes white. Every vertex is enqueued at most once.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

How many DEQUEUE operations? A non-white vertex never becomes white. Every vertex is enqueued at most once. At most O(|V|) DEQUEUE operations.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

- How many DEQUEUE operations? A non-white vertex never becomes white. Every vertex is enqueued at most once. At most O(|V|) DEQUEUE operations.
- For every dequeued vertex u, we spend O(|G.Adj[u]|) time.

- How many DEQUEUE operations? A non-white vertex never becomes white. Every vertex is enqueued at most once. At most O(|V|) DEQUEUE operations.
- ► For every dequeued vertex u, we spend O(|G.Adj[u]|) time. Total length of all adjacency-lists is O(|E|).

- How many DEQUEUE operations? A non-white vertex never becomes white. Every vertex is enqueued at most once. At most O(|V|) DEQUEUE operations.
- ► For every dequeued vertex u, we spend O(|G.Adj[u]|) time. Total length of all adjacency-lists is O(|E|).

• Total running time O(|V| + |E|).

For $u, v \in V$, let $\delta(u, v)$ be the minimum number of edges in a path between u and v in G, and ∞ if no such path exists.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

For $u, v \in V$, let $\delta(u, v)$ be the minimum number of edges in a path between u and v in G, and ∞ if no such path exists.

I.e., $\delta(u, v)$ is the **shortest path distance** between u and v in G.

For $u, v \in V$, let $\delta(u, v)$ be the minimum number of edges in a path between u and v in G, and ∞ if no such path exists.

I.e., $\delta(u, v)$ is the **shortest path distance** between u and v in G.

A path between u and v in G of length $\delta(u, v)$ is called a **shortest-path**.

Lemma For any $\{u, v\} \in E$, we have

 $\delta(s,v) \leq \delta(s,u) + 1.$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Lemma For any $\{u, v\} \in E$, we have

$$\delta(s, v) \leq \delta(s, u) + 1.$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Why?

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ □臣 = のへで

Proof.

Induction on the number of ENQUEUE operations.

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

Proof.

Induction on the number of ENQUEUE operations. Inductive hypothesis: For all $v \in V$, we have $v.d \ge \delta(s, v)$.

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

Proof.

Induction on the number of ENQUEUE operations. Inductive hypothesis: For all $v \in V$, we have $v.d \ge \delta(s, v)$. Basis of the induction: s.d = 0, and $v.d = \infty$ for all $v \ne s$.

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

Proof.

Induction on the number of ENQUEUE operations. Inductive hypothesis: For all $v \in V$, we have $v.d \ge \delta(s, v)$. Basis of the induction: s.d = 0, and $v.d = \infty$ for all $v \ne s$. Consider some $v \in G.Adj[u]$, immediately after dequeueing u.

Lemma

After the termination of BFS, for each $v \in V$, we have

 $v.d \geq \delta(s, v).$

Proof.

Induction on the number of ENQUEUE operations. Inductive hypothesis: For all $v \in V$, we have $v.d \ge \delta(s, v)$. Basis of the induction: s.d = 0, and $v.d = \infty$ for all $v \ne s$. Consider some $v \in G.Adj[u]$, immediately after dequeueing u.

$$egin{aligned} & v.d = u.d + 1 \ & \geq \delta(s,u) + 1 \ & \geq \delta(s,v) \end{aligned}$$
 (by the previous Lemma)

Lemma

Suppose during the execution, $Q = (v_1, ..., v_r)$, where $v_1 = head$, $v_r = tail$. Then for all $i \in \{1, ..., r - 1\}$

$$v_i.d \leq v_{i+1}.d,$$

and

 $v_r.d \leq v_1.d + 1.$

Lemma

Suppose during the execution, $Q = (v_1, ..., v_r)$, where $v_1 = head$, $v_r = tail$. Then for all $i \in \{1, ..., r - 1\}$

$$v_i.d \leq v_{i+1}.d,$$

and

$$v_r.d \leq v_1.d+1.$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Why?

Lemma

Suppose during the execution, both v_i and v_j are enqueued, and v_i is enqueued before v_j . Then, $v_i.d \leq v_j.d$ when v_j is enqueued.

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Lemma

Suppose during the execution, both v_i and v_j are enqueued, and v_i is enqueued before v_j . Then, $v_i.d \leq v_j.d$ when v_j is enqueued.

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Why?

Theorem

After termination, for all $v \in V$, we have

 $v.d = \delta(s, v).$

Moreover, for any v that is reachable from s, there exists a shortest path from s to v that consists of a shortest path from s to v. π , followed by the edge {v. π , v}.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$. Pick such a v so that $\delta(s, v)$ is minimized.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$. Pick such a v so that $\delta(s, v)$ is minimized. By the above Lemma, $v.d > \delta(s, v)$.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Pick such a v so that $\delta(s, v)$ is minimized.

By the above Lemma, $v.d > \delta(s, v)$.

Let u be the vertex preceding v in a shortest path from s to v. We have

$$v.d > \delta(s,v) = \delta(s,u) + 1 = u.d + 1.$$

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Pick such a v so that $\delta(s, v)$ is minimized.

By the above Lemma, $v.d > \delta(s, v)$.

Let u be the vertex preceding v in a shortest path from s to v. We have

$$v.d > \delta(s,v) = \delta(s,u) + 1 = u.d + 1.$$

Consider the time immediately after dequeueing u.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Pick such a v so that $\delta(s, v)$ is minimized.

By the above Lemma, $v.d > \delta(s, v)$.

Let u be the vertex preceding v in a shortest path from s to v. We have

$$v.d > \delta(s,v) = \delta(s,u) + 1 = u.d + 1.$$

Consider the time immediately after dequeueing u.

• If v is WHITE, then v.d = u.d + 1, a contradiction.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Pick such a v so that $\delta(s, v)$ is minimized.

By the above Lemma, $v.d > \delta(s, v)$.

Let u be the vertex preceding v in a shortest path from s to v. We have

$$v.d > \delta(s,v) = \delta(s,u) + 1 = u.d + 1.$$

Consider the time immediately after dequeueing u.

- If v is WHITE, then v.d = u.d + 1, a contradiction.
- If v is BLACK, then it is already dequeued, so by the above Lemma v.d ≤ u.d, a contradiction.

Suppose for the purpose of contradiction that there exists v with $v.d \neq \delta(s, v)$.

Pick such a v so that $\delta(s, v)$ is minimized.

By the above Lemma, $v.d > \delta(s, v)$.

Let u be the vertex preceding v in a shortest path from s to v. We have

$$v.d > \delta(s,v) = \delta(s,u) + 1 = u.d + 1.$$

Consider the time immediately after dequeueing u.

- If v is WHITE, then v.d = u.d + 1, a contradiction.
- If v is BLACK, then it is already dequeued, so by the above Lemma v.d ≤ u.d, a contradiction.
- If v is GRAY, then it was painted GRAY after dequeueing some vertex w, so v.d = w.d + 1 ≤ u.d + 1, a contradiction.

Proof sketch (cont.)

So, $v.d = \delta(s, v)$ for all $v \in V$.

Proof sketch (cont.)

So, $v.d = \delta(s, v)$ for all $v \in V$.

For the last part of the theorem, if $u = v.\pi$, then v.d = u.d + 1. The assertion follows by induction.

Breadth-first trees

We define the **predecessor graph** as $G_{\pi} = (V_{\pi}, E_{\pi})$, where

$$V_{\pi} = \{ v \in V : v \cdot \pi \neq \mathsf{NIL} \} \cup \{ s \}$$
$$E_{\pi} = \{ (v \cdot \pi, v) : v \in V_s \setminus \{ s \} \}$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

Breadth-first trees

We define the **predecessor graph** as $G_{\pi} = (V_{\pi}, E_{\pi})$, where

$$V_{\pi} = \{ v \in V : v \cdot \pi \neq \mathsf{NIL} \} \cup \{ s \}$$
$$E_{\pi} = \{ (v \cdot \pi, v) : v \in V_s \setminus \{ s \} \}$$

 G_{π} is a **breadth-first tree** if V_{π} consists of the vertices reachable from *s* and for all $v \in V_{\pi}$, G_{π} contains a unique simple path from *s* to *v* that is also a shortest path from *s* to *v* in *G*.

Breadth-first trees

We define the **predecessor graph** as $G_{\pi} = (V_{\pi}, E_{\pi})$, where

$$V_{\pi} = \{ v \in V : v \cdot \pi \neq \mathsf{NIL} \} \cup \{ s \}$$
$$E_{\pi} = \{ (v \cdot \pi, v) : v \in V_s \setminus \{ s \} \}$$

 G_{π} is a **breadth-first tree** if V_{π} consists of the vertices reachable from *s* and for all $v \in V_{\pi}$, G_{π} contains a unique simple path from *s* to *v* that is also a shortest path from *s* to *v* in *G*.

Lemma

After the execution of BFS, the predecessor graph G_{π} is a breadth-first tree.